Ultrasonic Distance Sensor for Robo:Bit Mk2

Ready-Soldered, just attach to your Robo:Bit Mk2using the 4 screws included and off you go.

Use Microsoft PXT (or MicroPython with some awkward code) to read the distance to an obstacle, then program your Robo:Bit to avoid it.

Both Ping and Echo signals are on the same pin (Pin 13) (NB. this is a different pin to Bit:Bot